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second edition. Dr. Jeff Kerr wrote the first draft of Chapter 8. Prof. Robert L. Williams II contributed the MATLAB exercises found at the end of each chapter, and Peter Corke expanded his Robotics Toolbox to support this book's style of the Denavit–Hartenberg notation. I owe a debt to my previous mentors in robotics:

Artificial Intelligence: A Modern Approach

The current version of the book is the updated first edition (online preprint dated December 2019, printed published version from Cambridge marked "3rd printing 2019" or later). The updated first edition (also referred to as "version 2") includes several corrections and minor additions to the original first edition (first published in May 2017).

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About the third edition. This third edition contains two major additions: In Chapter 7, on Voronoi diagrams, we now also discuss Voronoi diagrams of line segments and farthest-point Voronoi diagrams. In Chapter 12, we have included an extra section on binary space partition trees for low-density scenes, as an introduction to realistic input models.

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